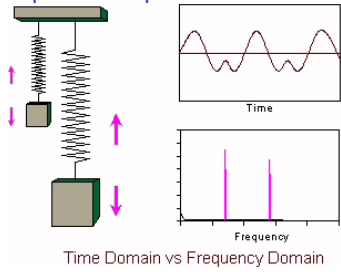


Vibration Reference Guide

Basic Vibration Theory

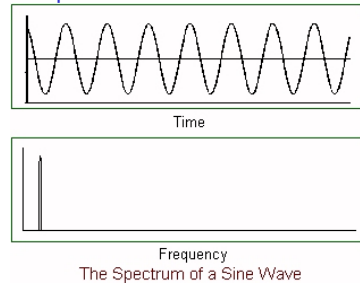
Time vs. Frequency Analysis

Individual frequency components are separate in spectrum



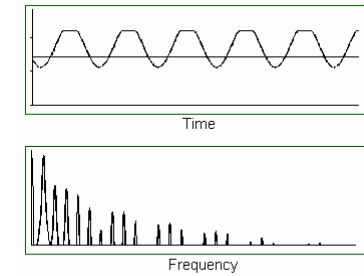
Rule 1 for Frequency Analysis

A sine wave only has one frequency component



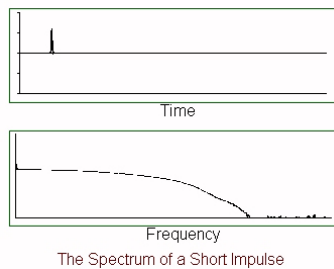
Rule 2 for Frequency Analysis

Periodic signals in machinery produce Harmonics



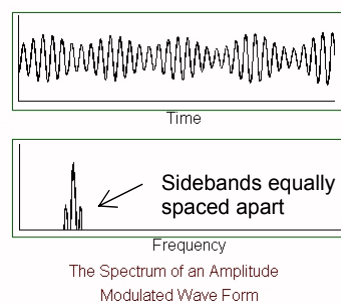
Rule 3 for Frequency Analysis

An impulse or random noise produces a continuous spectrum



Rule 4 for Frequency Analysis

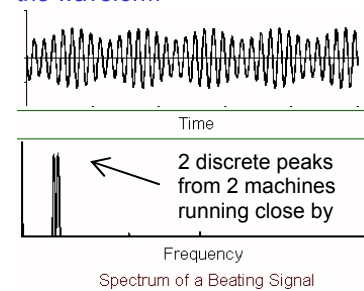
Amplitude Modulation produces Sidebands (e.g. gear fault)



The Spectrum of a Periodic Signal

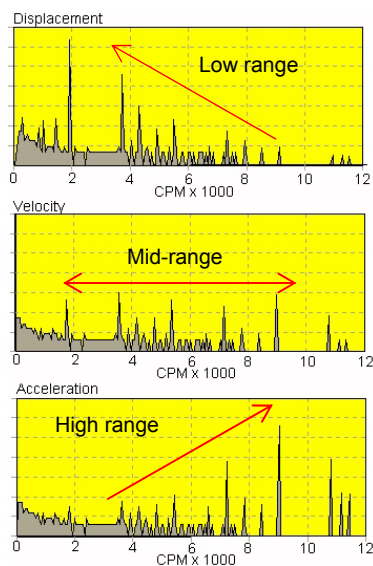
Rule 5 for Frequency Analysis

Beats look like amplitude modulation in the waveform

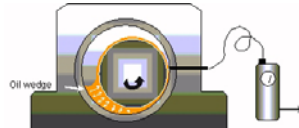


Presentation of Data

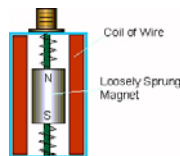
Each curve below contains the same information! Select the units for the flattest curve – provides the most visual information. Displacement (distance from a reference point) is used for low speeds. Velocity (rate of change of displacement) is the most commonly used for machine diagnostic work. Acceleration (rate of change of velocity) is used for high-speeds.



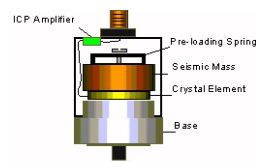
Vibration Transducers



Proximity Probe Displacement



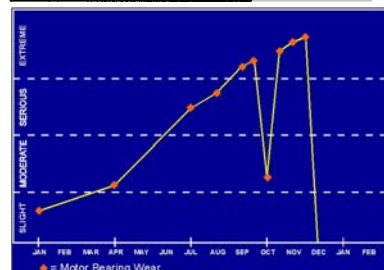
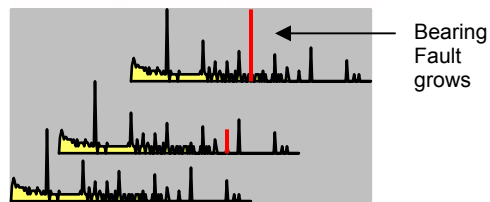
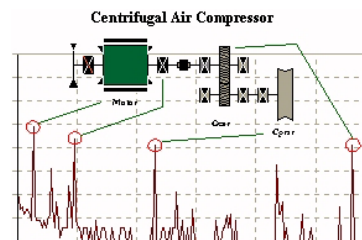
Velocity Probe - Velocity



Accelerometer Acceleration

Vibration Analysis – 3 Step Process

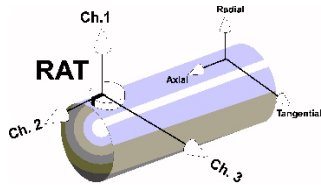
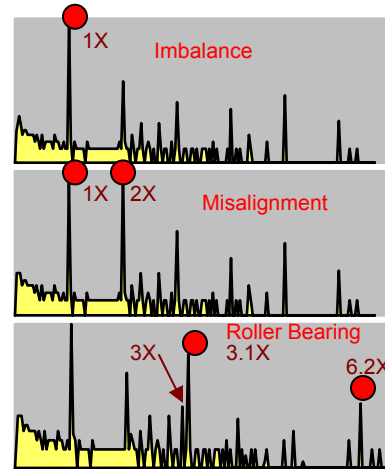
1. **Identify Peaks:** Relationship to machine component
2. **Trend Amplitude of Peak:** Severity of machine fault
3. **Repair Priority:** Based on fault severity



Vibration Reference Guide

Simplified Diagnostic Chart

<u>Vibration Source</u>	<u>Exciting Freq.</u>	<u>Dominant Axes</u>	<u>Comments</u>
<u>Imbalance</u> , Supported	1X	R & T	Most common
<u>Imbalance</u> , Overhung	1X	A, R, T	Axial deflection
<u>Bent or bowed shaft</u>	1X	A, R, T	Mimic imbalance
<u>Parallel misalignment</u>	2X	R & T	Both sides of coupling
<u>Angular misalignment</u>	1X	A	Both sides of coupling
<u>Combination</u>	1X, 2X	A, R, T	Most common
<u>Coupling Wear</u>	3X	any, all	Both sides of coupling
<u>Rolling Bearing</u>	Non Integer	R, T, A	With harmonics, 1X sidebands, noise floor
<u>Shaft Looseness</u> And Journal Bearing	1X and Harmonics	R, T, A	High 4X – 15X
<u>Foundation flexibility</u>	1X	T	T > R by 6 dB
<u>Motor Lamination</u>	MB	R, T, A	120 Hz sidebands (twice line freq.)
<u>Unbalanced Phase</u>	120 Hz	R, T, A	Twice line freq
<u>Fan or Pump wear</u>	PV or FB	R, T, A	Vane or blade pass freq. and harmonics
<u>Cavitation</u>	Noise	R, T, A	Hump of random high freq. noise 20X – 50X



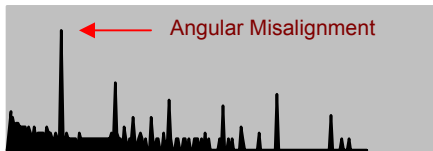
3 Axes of Data
Horizontal Shaft:
Radial = Vertical
Tangential = Horiz.

2 Frequency Ranges
Low Range = 0-10 Orders of shaft rotation
High Range = 0-100 Orders of shaft rotation

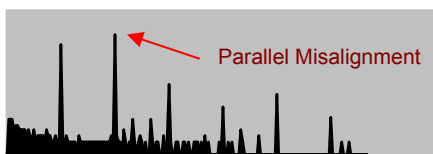
3 Axis and 2 Frequency Ranges

Low Range Data

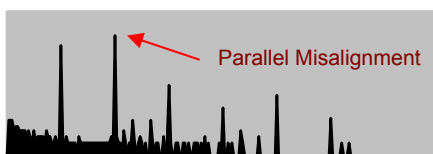
Imbalance, Misalignment, Bearings, Fan blades, Pump Impeller, Looseness, Foundation Flexibility



Axial
(Axial)



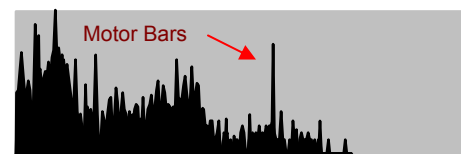
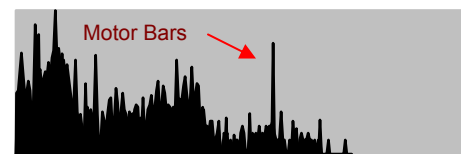
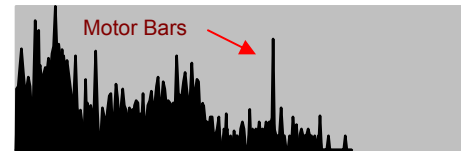
Vertical
(Radial)



Horizontal
(Tangential)

High Range Data

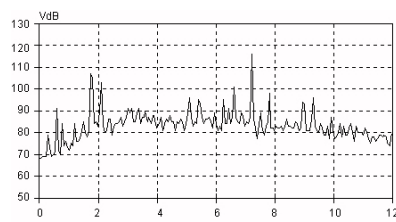
First bearing fault indication, Motor Bars, Gear Mesh, Turbine vanes, harmonics



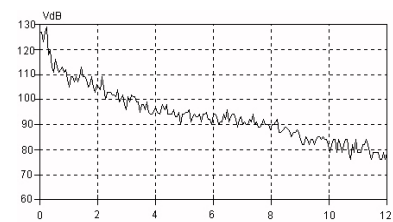
Data Validity

Bad Data comes from:

- Improper test conditions
- Wrong machine tested
- Sensor amplifier problem
- Incorrect orientation



Loose Sensor (magnet mount)



Overheated sensor (ski slope)